**About the project**

To goal is to create an algorithm to determine the most efficient path for a drone to visit each point of interest in the shortest distance.

**How it adds value**

* Saves fuel
* Saves time
* Safer and cheaper than human-operated aircraft
* Provides easy interface to show routes and data about our points of interest

**Context: How it relates to real-world problems**

* Seeing drone technology become cheaper and more widespread
* New methods in machine learning and big data bring more value to large amounts of footage

**Potential future improvements**

* Completing the 600km SD card swap
* More perfected algorithms, which will be more expensive and time-consuming to compute
* Comparing different algorithms to determine with ones are better
* Considering other variables such as altitude, wind-speed
* Avoiding collision with other aircrafts and birds
* Determining best paths when there are multiple drones
* Moving points of interest

**Mission Control**

**The challenge**

**How it Works**

**Demo**

**Value?**

**Future Improvements**